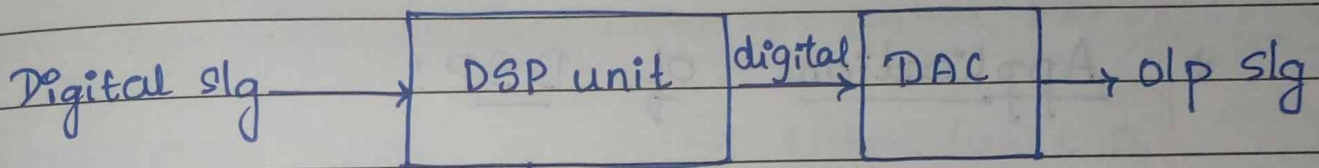
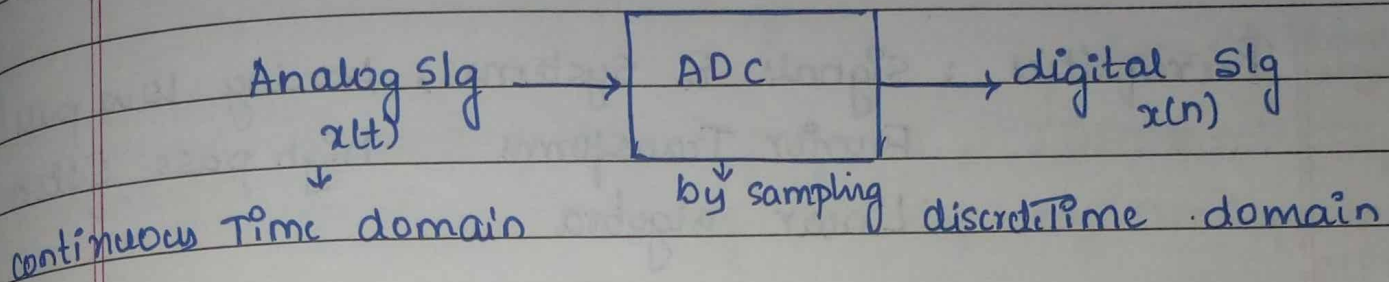


Intro to DSP: "Digital Signal Processing"

- * All slgs in nature are Analog slg
- * But to process we require Digital slgs. to do real tym slg processing



We can use filters to remove noise slg

Filters → FIR (Finite impulse response filters)
IIR (Infinite " " " ")

Levels of slg processing:

- 1] System level ⇒ can use 'C' programming, python, any image processing tool, Audio processing tool or matlab, Simulink and so on.

2] Board level $\Rightarrow$ FPGA, Transistor level
(chip level)
Ex: mobile

* Analog sigs are captured by sensors/hardware

Prerequisites: signals & systems, Analog low pass/
Fourier Transforms high pass filters
Linear algebra

* Applications of DSP:

In various fields we use DSP

- ① Stock market analysis: to know when profits are peak
- ② Biomedical: ECG, EEG analysis
- ③ Radar sig processing: to detect targets
- ④ Sonar sig " : in sea to navigate
- ⑤ Communicatⁿ sigs: Image/Audio processing
- ⑥ Audio, Video: Speaker Recognitⁿ, Cepstral analysis
- ⑦ Seismic
- ⑧ Satellite/Rocket testing

2 types of analysis

- $\rightarrow$ Time domain analysis:
- $\rightarrow$ Frequency " "
- $\rightarrow$ Noise Removal

Filters $\rightarrow$ Butterworth
 $\rightarrow$ IIR $\rightarrow$ Chebyshev
 $\rightarrow$ FIR $\rightarrow$ windows filter

Unit I: ① DFT (Discrete Fourier Transform), IDFT $\Rightarrow$ properties $\rightarrow$ Goertzel Chip-z algorithm

DFT in linear filtering, overlap add, Overlap method

convolutⁿ mechanism

Unit II: Filters

② FFT (fast Fourier transform) $\rightarrow$ 2+4 steps algorithm, DFT/IFFT, DIT FFT, DIF FFT

chapter ③: Design of digital filters (unit II)

FIR filters: types, methods of designing filters

④ IIR filters $\rightarrow$

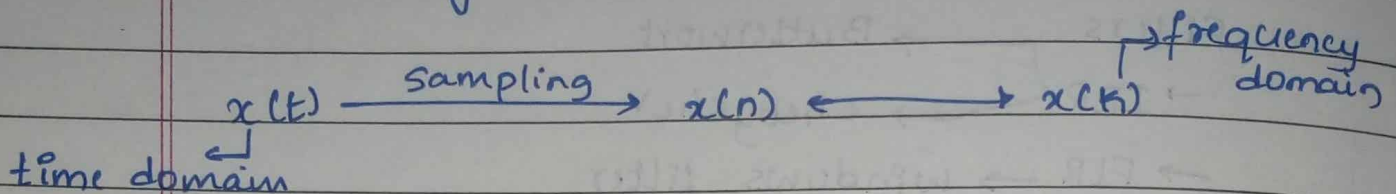
Unit III: chapter ⑤ Digital Realizatⁿs for FIR filters

" ⑥ " " " IIR filters

Time and frequency domain Signals:

$x(t)$ → analog domain

$x(n)$ → digital domain



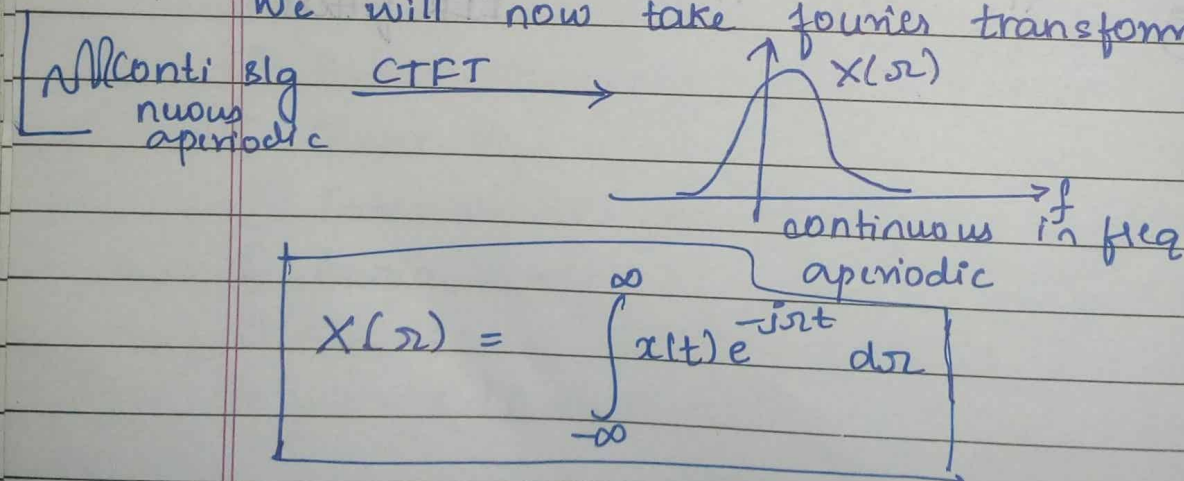
→ Freq domain Sampling and Reconstructⁿ of discrete time signals.

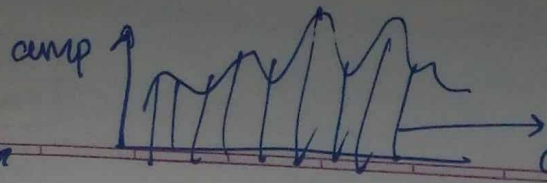
→ Why DFT (Discrete Fourier Transform) ?

We cannot process a signal directly through digital signal processor

So we will take a part of sig in tym domain $x(t)$ w is continuous in time and Aperiodic in nature.

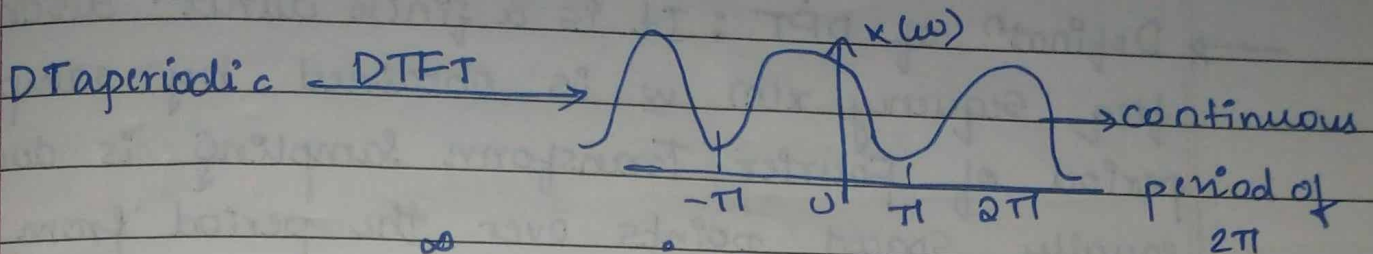
We will now take fourier transform of that





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Now we sample the sig with sampling freq using nyquist criteria



$$X(\omega) = \sum_{n=-\infty}^{\infty} x(n) e^{-j\omega n}$$

$$\omega = \frac{2\pi k}{N} \quad N = \text{total number of samples}$$

$$X\left(\frac{2\pi k}{N}\right) = \sum_{n=0}^{N-1} x(n) e^{-j\frac{2\pi k n}{N}}$$

$$\boxed{X(k) = \sum_{n=0}^{N-1} x(n) e^{-j\frac{2\pi k n}{N}}} \quad k = 0, 1, 2, \dots, N-1$$

→ This can be matched to discrete DS processors

IDFT (Inverse discrete Fourier Transform)

$$x(n) = \frac{1}{N} \sum_{k=0}^{N-1} X(k) e^{j\frac{2\pi k n}{N}}$$

This is known as N pt IDFT.

* Definitⁿ of DFT and IDFT:

→ Definitⁿ of DFT: It is a finite duratⁿ discrete freq sequence $x(n)$ $\xrightarrow{X(k)}$ is obtained by sampling one period of Fourier Transform sampling is done at N equally spaced points over the period from $\omega=0$ to 2π

$$\text{DFT} \Rightarrow \begin{matrix} x(n) & \xleftrightarrow{\text{DFT}} & X(k) \\ & \text{IDFT} & \end{matrix} \quad \begin{matrix} \downarrow \\ \text{freq domain} \end{matrix} \quad \begin{matrix} \xrightarrow{X(k)} \\ \text{tym domain} \end{matrix}$$

$$X(k) = \sum_{n=0}^{N-1} x(n) e^{-j\frac{2\pi nk}{N}} \quad k=0,1,2,\dots,N-1$$

$$\text{IDFT} \Rightarrow x(n) = \frac{1}{N} \sum_{k=0}^{N-1} X(k) e^{j\frac{2\pi nk}{N}}, \quad n=0,1,\dots,N-1$$

Twiddle factor notation

$$W_N = e^{-j\frac{2\pi}{N}}$$

→ Twiddle factor

$$\therefore \text{DFT} \rightarrow X(k) = \sum_{n=0}^{N-1} x(n) W_N^{kn} \quad k=0,1,2,\dots,N-1$$

$$\text{IDFT} \rightarrow x(n) = \frac{1}{N} \sum_{k=0}^{N-1} X(k) W_N^{-kn} \quad \begin{matrix} k=0,1,2,\dots,N-1 \\ n=0,1,2,\dots,N-1 \end{matrix}$$

* Twiddle factors and Zero Padding :

$$W_N = e^{-j\frac{2\pi}{N}}$$
 is twiddle factor

$$N = 2, 4, 8, 16, \dots$$

W.K.T $e^{j\theta} = \cos\theta - j\sin\theta$

For $N=2$

$$W_N = e^{-j\frac{2\pi}{N}} = e^{-j\pi}$$

$$= \cos\pi - j\sin\pi$$

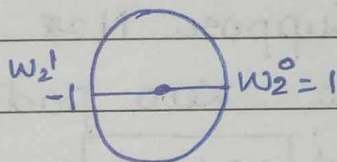
$$W_2 = -1$$

$$W_N^K = e^{-j\frac{2\pi K}{N}}$$

$$\rightarrow W_2^0 = e^{-j\frac{2\pi \cdot 0}{2}} = 1$$

$$\rightarrow W_2^1 = e^{-j\frac{2\pi \cdot 1}{2}} = e^{-j\pi} = -1$$

Euler's diagram is



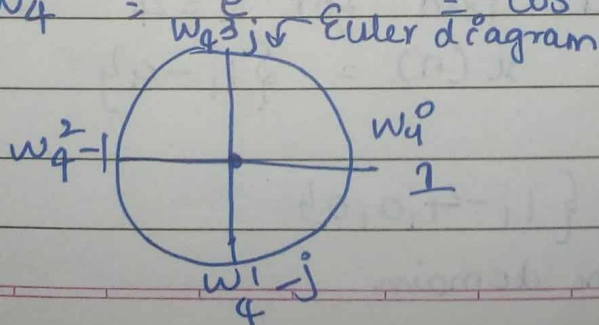
When $N=4$ $W_4^K = e^{-j\frac{2\pi K}{4}} = e^{-j\pi K/2}$

$$W_4^0 = e^{-j\pi \cdot 0} = 1$$

$$W_4^1 = e^{-j\pi/2} = \cos\pi/2 - j\sin\pi/2 = -j$$

$$W_4^2 = e^{-j\pi} = -1$$

$$W_4^3 = e^{-j3\pi/2} = \cos 3\pi/2 - j\sin 3\pi/2 = j$$



When $N=8$, $W_8^k = e^{-j2\pi k/8} = e^{-j\frac{\pi k}{4}}$

$W_8^0 = 1$

$W_8^4 = -1$

$W_8^1 = 0.707 - j0.707$

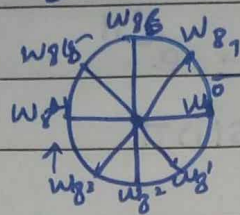
$W_8^5 = -0.707 + j0.707 \rightarrow \frac{1}{\sqrt{2}}$

$W_8^2 = -j$

$W_8^6 = +j$

$W_8^3 = -0.707 - j0.707$

$W_8^7 = 0.707 + j0.707$



→ Euler's diagram

→ Zero Padding: Used in signal processing applications
↳ Adding slgs of '0' Amplitude in the time domain to end of sequence

$x(kn)$

↳ Time index

Suppose $N=8$ & we have only $\{1, 1, 1, 1\}$
then we are going to zero pad remaining 5
i.e., $\{1, 1, 1, 1, \dots\}$

↳ going to end slg with '0' Amplitude, not adding any info only extending the slg with 0 Amplitude

→ If I have to zero pad for $N=4$
given slg is $x(n) = \{1, -4\}$

Ans is $x(n) = \{1, -4, 0, 0\}$

↳ Time domain

* DFT as a linear Transformation: (Matrix method)

let input signal be $x_N = \begin{bmatrix} x_0 \\ x_1 \\ \vdots \\ x_{N-1} \end{bmatrix}_{N \times 1}$

$X_N = \begin{bmatrix} x(0) \\ x(1) \\ \vdots \\ x(N-1) \end{bmatrix}_{N \times 1} \rightarrow \text{freq domain}$

By defⁿ

$$X(k) = \sum_{n=0}^{N-1} x(n) e^{-j \frac{2\pi nk}{N}}$$

$$W_N = e^{-j \frac{2\pi}{N}}$$

$$\therefore X(k) = \sum_{n=0}^{N-1} x(n) W_N^{kn}$$

let $N=4$, $\therefore x(n) = [x(0), x(1), x(2) \& x(3)] \rightarrow \text{Time domain}$

In freq domain $\{x(0), x(1), x(2), x(3)\}$

$$W_4^0 = 1 \quad W_4^1 = j \quad W_4^2 = -1 \quad W_4^3 = -j \quad (\text{W.K.T})$$

$$\text{DFT } X(k) = [W_N] x_N$$

$$X(k) = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -j & -1 & j \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{bmatrix} x_N$$

↑ (complex conjugate)

$$\text{IDFT } x(n) = \frac{1}{N} \sum_{k=0}^{N-1} W_N^{nk} X(k)$$

$$= \frac{1}{N} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & j & -1 & -j \\ 1 & -1 & 1 & -1 \\ 1 & -j & -1 & j \end{bmatrix} X(k)$$

here $N=4$

$$\therefore \frac{1}{4} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & j & -1 & -j \\ 1 & -1 & 1 & -1 \\ 1 & -j & -1 & j \end{bmatrix} X(k)$$

PROPERTIES OF DFT:

①* Linearity & Periodicity Property

1] LINEARITY :-

Suppose we have sig $x_1(n)$ & its DFT is $X_1(k)$

$$x_1(n) \xrightarrow{\text{DFT}} X_1(k)$$

$$x_2(n) \xrightarrow{\text{DFT}} X_2(k)$$

then, property states

$$a_1 x_1(n) + a_2 x_2(n) \xrightarrow{\text{DFT}} a_1 X_1(k) + a_2 X_2(k) //$$

W.K.T $X_1(k) = \sum_{n=0}^{N-1} x_1(n) e^{-j2\pi nk/N}$

& $X_2(k) = \sum_{n=0}^{N-1} x_2(n) e^{-j2\pi nk/N}$

$$\text{DFT } \{a_1 x_1(n) + a_2 x_2(n)\} = \sum_{n=0}^{N-1} [a_1 x_1(n) + a_2 x_2(n)] e^{-j2\pi nk/N}$$

$$= \sum_{n=0}^{N-1} a_1 x_1(n) e^{-j2\pi nk/N} + \sum_{n=0}^{N-1} a_2 x_2(n) e^{-j2\pi nk/N}$$

$$\text{DFT } \{a_1 x_1(n) + a_2 x_2(n)\} = a_1 X_1(k) + a_2 X_2(k) //$$

hence proved.

2] PERIODICITY:

$$x(n) \xrightarrow{\text{DFT}} X(k)$$

$$x(n+N) = x(n)$$

$$X(k+N) = X(k)$$

$$X(k+N) = \sum_{n=0}^{N-1} x(n) e^{-j2\pi n(k+N)/N}$$

$$= \sum_{n=0}^{N-1} x(n) e^{-j2\pi nk/N} e^{-j2\pi nN/N} \quad \because e^{-j2\pi n} = 1$$

$$X(k+N) = X(k) \rightarrow \text{hence proved.}$$

3] CIRCULAR TIME SHIFT PROPERTY:

If a discrete time signal is circularly shifted in time by m units then its DFT is multiplied by $e^{-j2\pi km/N}$

If $x(n) \xleftrightarrow{\text{DFT}} X(k)$ then $x(n-m)_N \xleftrightarrow{\text{DFT}} X(k) e^{-j2\pi km/N}$

$$x(n-m)_N \xleftrightarrow{\text{DFT}} X(k) e^{-j2\pi km/N}$$

Let $p = n-m$
 $n = p+m$

$$\text{DFT}\{x(n-m)_N\} = \sum_{n=0}^{N-1} x(p)_N e^{-j2\pi km/N}$$

$$= \sum_{n=0}^{N-1} x(p)_N e^{-j2\pi kp/N} \cdot e^{-j2\pi km/N}$$

$$\text{DFT}\{x(n-m)_N\} = X(k) e^{-j2\pi km/N} \quad // \text{ hence proved.}$$

4] TIME REVERSAL:

Reversing N point sequence in time is equivalent to reversing the DFT sequence

If $\text{DFT}\{x(n)\} = X(k)$

$\text{DFT}\{x(N-n)\} = X(N-k) \quad //$

proof $\text{DFT}\{x(N-n)\} = \sum_{n=0}^{N-1} x(N-n) e^{-j2\pi nk/N}$

let

$m = N-n \quad m = N-n$

$n = N-m$

$$= \sum_{n=0}^{N-1} x(m) e^{-j2\pi k(N-m)/N}$$

$[e^{-j2\pi k} = 1]$

$$\text{DFT}\{x(N-n)\} = \sum_{n=0}^{N-1} x(m) e^{-j2\pi k(N-m)/N} e^{j2\pi km/N}$$

$$= \sum_{n=0}^{N-1} x(m) e^{-j2\pi km/N} e^{j2\pi km/N} \quad [e^{-j2\pi km} = 1]$$

$$\text{DFT}\{x(N-n)\} = \sum_{n=0}^{N-1} x(m) e^{-j2\pi km/N} (N-k)$$

$\therefore \text{DFT}\{x(N-n)\} = X(N-k) \quad // \text{ hence proved.}$

5] Conjugation:

let $x(n)$ be a complex N point discrete sequence & $x^*(n)$ be its complex conjugate. Now if

$\text{DFT}\{x(n)\} = X(k)$ then

$\text{DFT}\{x^*(n)\} = X^*(N-k)$

$$\text{DFT}\{x^*(n)\} = \sum_{n=0}^{N-1} x^*(n) e^{-j2\pi nk/N}$$

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$$\begin{aligned}
 &= \left[\sum_{n=0}^{N-1} x(n) e^{j \frac{2\pi nk}{N}} \right]^* \\
 &\quad \text{W.K.T } e^{j 2\pi n} = 1 \\
 &= \left[\sum_{n=0}^{N-1} x(n) e^{j \frac{2\pi nk}{N}} e^{-j \frac{2\pi nk}{N}} \right]^* \\
 &= \left[\sum_{n=0}^{N-1} x(n) e^{-j \frac{2\pi nk}{N}} e^{-j \frac{2\pi nk}{N}} \right]^* \\
 &= \left[\sum_{n=0}^{N-1} x(n) e^{-j \frac{2\pi nk}{N}} \right]^* \\
 &= [X(N-k)]^* \\
 &= X^*(N-k) // \text{ hence proved.}
 \end{aligned}$$

6] CIRCULAR FREQUENCY SHIFT PROPERTY:

The circular frequency shift property of DFT says that if a discrete time signal is multiplied by $e^{j \frac{2\pi mn}{N}}$ = $X((k-m))_N$

proof:

→ If $\text{DFT}\{x(n)\} = X(k)$ then
 $\text{DFT}\left\{x(n) e^{j \frac{2\pi mn}{N}}\right\} = X((k-m))_N$

$$\text{DFT}\left\{x(n) e^{j \frac{2\pi mn}{N}}\right\} = \sum_{n=0}^{N-1} x(n) e^{j \frac{2\pi mn}{N}} e^{-j \frac{2\pi nk}{N}}$$

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$$\begin{aligned}
 &= \sum_{n=0}^{N-1} x(n) e^{-j \frac{2\pi (k-m)n}{N}} \\
 &= X((k-m))_N // \text{ hence proved}
 \end{aligned}$$

DTFT TO DFT:-

→ Sampling and reconstruction of discrete time signals:-
 W.K.T Aperiodic finite energy signals have continuous spectra

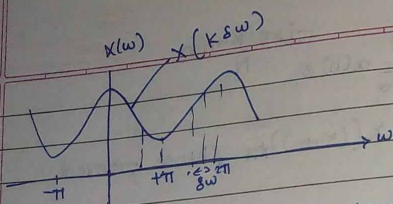
Let us consider Aperiodic discrete time sig $x(n)$ with fourier transform $X(\omega) = \sum_{n=-\infty}^{\infty} x(n) e^{-j\omega n}$

→ We will sample periodically in frequency domain and we will keep spacing 2π samples and 2π radians.

W.K.T $X(\omega)$ is periodic, period is 2π

If we take only samples of the fundamental freq range That is enough

Let us take N equidistant samples in the interval $0 \leq \omega < 2\pi$ with spacing $\Delta\omega = \frac{2\pi}{N}$



Freq domain sampling of fourier transform

consider N number of samples in freq domain

$$X(\omega) = \sum_{n=-\infty}^{\infty} x(n) e^{-j\omega n}$$

Evaluate this @ $\omega = \frac{2\pi k}{N}$

$$X\left(\frac{2\pi k}{N}\right) = \sum_{n=-\infty}^{\infty} x(n) e^{-j \frac{2\pi k n}{N}}$$

↳ subdivides RHS summat

each should have only N terms

$$X\left(\frac{2\pi k}{N}\right) = \sum_{n=-N}^{-1} x(n) e^{-j \frac{2\pi k n}{N}} + \sum_{n=0}^{N-1} x(n) e^{-j \frac{2\pi k n}{N}} + \dots$$

$$\sum_{n=N}^{2N-1} x(n) e^{-j \frac{2\pi k n}{N}} + \dots$$

$$X\left(\frac{2\pi k}{N}\right) = \sum_{l=-\infty}^{\infty} \sum_{n=1N}^{(l+1)N-1} x(n) e^{-j \frac{2\pi k n}{N}}$$

change $n \Rightarrow n-lN$ & interchange the summat's

$$X\left(\frac{2\pi k}{N}\right) = \sum_{n=0}^{N-1} \sum_{l=-\infty}^{\infty} x(n-lN) e^{-j \frac{2\pi k (n-lN)}{N}}$$

$$\text{let } x_p(n) = \sum_{l=-\infty}^{\infty} x(n-lN)$$

fourier series expansion of $x_p(n)$ is

$$\text{w.k.T } x_p(n) = \sum_{k=-\infty}^{\infty} C_k e^{j \frac{2\pi k n}{N}}$$

C_k = fourier coefficient

$$C_k = \frac{1}{N} \sum_{n=0}^{N-1} x_p(n) e^{-j \frac{2\pi k n}{N}}$$

$$\therefore x_p(n) = \frac{1}{N} \sum_{k=0}^{N-1} X\left(\frac{2\pi k}{N}\right) e^{j \frac{2\pi k n}{N}}$$

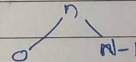
↳ It provides reconstruct of periodic sig $x_p(n)$ from $X(\omega)$

let Relationship bt $x_p(n)$ and $x(n)$

for $x(n)$ $N \geq L \rightarrow$ no aliasing

$N < L \rightarrow$ aliasing

Conclusion: spectrum of an aperiodic discrete time signal with finite duratⁿ (L) can be exactly recovered from samples $w_k = \frac{2\pi k}{N}$ if $\underline{N \geq L}$



CIRCULAR CONVOLUTION

$$x_1(n) \otimes x_2(n) = \sum_{m=0}^{N-1} x_1(m) x_2((n-m)_N)$$

property

If $\text{DFT}\{x_1(n)\} = X_1(k)$ & $\text{DFT}\{x_2(n)\} = X_2(k)$ then
 $\text{DFT}\{x_1(n) \otimes x_2(n)\} = X_1(k) X_2(k)$

proof: $X_1(k) = \sum_{n=0}^{N-1} x_1(n) e^{-j2\pi nk/N}$

change n to m
 $X_1(k) = \sum_{m=0}^{N-1} x_1(m) e^{-j2\pi mk/N}$

$X_2(k) = \sum_{n=0}^{N-1} x_2(n) e^{-j2\pi nk/N}$ change $n \rightarrow p$

$X_2(k) = \sum_{p=0}^{N-1} x_2(p) e^{-j2\pi pk/N}$

$\text{IDFT} : \text{DFT}^{-1}\{X_1(k) X_2(k)\} = \frac{1}{N} \sum_{k=0}^{N-1} X_1(k) X_2(k) e^{j2\pi nk/N}$

$$= \frac{1}{N} \sum_{k=0}^{N-1} \left[\sum_{m=0}^{N-1} x_1(m) e^{-j2\pi mk/N} \right] \left[\sum_{p=0}^{N-1} x_2(p) e^{-j2\pi pk/N} \right] e^{j2\pi nk/N}$$

$$= \frac{1}{N} \sum_{m=0}^{N-1} x_1(m) \sum_{p=0}^{N-1} x_2(p) \sum_{k=0}^{N-1} e^{j2\pi k(n-m-p)/N}$$

let $n-m-p = qN$ q is integer

$$\therefore \sum_{k=0}^{N-1} e^{j2\pi k(n-m-p)/N} = \sum_{k=0}^{N-1} e^{j2\pi kqN/N} = \sum_{k=0}^{N-1} (e^{j2\pi q})^k = \sum_{k=0}^{N-1} 1^k = N$$

and $\sum_{p=0}^{N-1} x_2(p) = \sum_{m=0}^{N-1} x_2(n-m-qN) = \sum_{m=0}^{N-1} x_2(n-m)_{\text{mod } N}$

$$= \sum_{m=0}^{N-1} x_2((n-m)_N)$$

$\therefore \text{DFT}\{X_1(k) X_2(k)\} = \frac{1}{N} \sum_{m=0}^{N-1} x_1(m) \sum_{n=0}^{N-1} x_2((n-m)_N) \cdot N$

$$= \sum_{m=0}^{N-1} x_1(m) x_2((n-m)_N)$$

$$= x_1(n) \star x_2(n)$$

$\therefore X_1(k) X_2(k) = \text{DFT}\{x_1(n) \otimes x_2(n)\} //$

MULTIPLICATION PROPERTY OF DFT:

If $\text{DFT}\{x_1(n)\} = X(k)$ & then
 $\text{DFT}\{x_1(n)x_2(n)\} = \frac{1}{N} [X_1(k) \otimes X_2(k)]$

$$\begin{aligned} x_1(n) &= \frac{1}{N} \sum_{k=0}^{N-1} X_1(k) e^{j2\pi kn/N} = \frac{1}{N} \sum_{m=0}^{N-1} X_1(m) e^{j2\pi mn/N} \quad \because k=m \\ \text{DFT}\{x_1(n)x_2(n)\} &= \sum_{n=0}^{N-1} x_1(n)x_2(n) e^{-j2\pi kn/N} \\ &= \sum_{n=0}^{N-1} \left[\frac{1}{N} \sum_{m=0}^{N-1} X_1(m) e^{j2\pi mn/N} \right] x_2(n) e^{-j2\pi kn/N} \\ &= \frac{1}{N} \sum_{m=0}^{N-1} X_1(m) \left[\sum_{n=0}^{N-1} x_2(n) e^{-j2\pi n(k-m)/N} \right] \\ &= \frac{1}{N} \sum_{m=0}^{N-1} X_1(m) \left[\sum_{n=0}^{N-1} x_2(n) e^{-j2\pi n(k-m)/N} \right] \\ &= \frac{1}{N} \sum_{m=0}^{N-1} X_1(m) X_2((k-m))_N = \frac{1}{N} [X_1(k) \otimes X_2(k)] \end{aligned}$$

$\therefore \text{DFT}\{x_1(n)x_2(n)\} = \frac{1}{N} [X_1(k) \otimes X_2(k)]$
 hence proved

CIRCULAR CORRELATION:

If we have 2 f/p s/s $x(n)$ and $y(n)$ then my circular correlation property

$$\bar{r}_{xy}(m) = \sum_{n=0}^{N-1} x(n) y^*((n-m))_N$$

If $\text{DFT}\{x(n)\} = X(k)$ & $\text{DFT}\{y(n)\} = Y(k)$
 By correlation property

$$\text{DFT}\{\bar{r}_{xy}(m)\} = \text{DFT}\left\{ \sum_{n=0}^{N-1} x(n) y^*((n-m))_N \right\}$$

proof: $X(k) = \sum_{n=0}^{N-1} x(n) e^{-j2\pi nk/N}$ and $Y(k) = \sum_{n=0}^{N-1} y(n) e^{-j2\pi nk/N}$
 $Y(k) = \sum_{p=0}^{N-1} y(p) e^{-j2\pi kp/N}$

$$\begin{aligned} \text{DFT}\{\bar{r}_{xy}(m)\} &= \frac{1}{N} \sum_{k=0}^{N-1} X(k) Y^*(k) e^{j2\pi km/N} \\ &= \frac{1}{N} \sum_{k=0}^{N-1} \left[\sum_{n=0}^{N-1} x(n) e^{-j2\pi nk/N} \right] \left[\sum_{p=0}^{N-1} y(p) e^{-j2\pi kp/N} \right]^* e^{j2\pi km/N} \\ &= \frac{1}{N} \sum_{n=0}^{N-1} x(n) \sum_{p=0}^{N-1} y^*(p) \sum_{k=0}^{N-1} e^{j2\pi k(m-n+p)/N} \end{aligned}$$

let us consider this part.

consider $\sum_{k=0}^{N-1} e^{\frac{j2\pi k(m-n)p}{N}}$, let $m-n+p=qN$ $\rightarrow$ integer

$$= \sum_{k=0}^{N-1} e^{j2\pi kqN/N} = \sum_{k=0}^{N-1} (j2\pi q)^k$$

$$= \sum_{k=0}^{N-1} 1^k = N$$

$\therefore$ let us take $\sum_{p=0}^{N-1} y^*(p)$ from that eqn

let $m-n+p=qN$
 $p = n-m+qN$

$$\therefore \sum_{p=0}^{N-1} y^*(p) = \sum_{n=0}^{N-1} y^*(n-m+qN)$$

$$= \sum_{n=0}^{N-1} y^*(n-m), \text{ mod } N$$

$$\sum_{p=0}^{N-1} y^*(p) = \sum_{n=0}^{N-1} y^*((n-m)_N)$$

$$\therefore \text{DFT}^{-1}\{X(k) \otimes Y^*(k)\} = \frac{1}{N} \sum_{n=0}^{N-1} x(n) \sum_{m=0}^{N-1} y^*((n-m)_N) \cdot N$$

$$= \sum_{n=0}^{N-1} x(n) y^*((n-m)_N)$$

$$= \bar{y}_y(m)$$

$$\therefore X(k)Y^*(k) = \text{DFT}\{\bar{y}_y(m)\} //$$

PARSEVAL'S THEOREM (energy)

If $\text{DFT}\{x_1(n)\} = X_1(k)$ & $\text{DFT}\{x_2(n)\} = X_2(k)$ then

$$\sum_{n=0}^{N-1} x_1(n)x_2^*(n) = \frac{1}{N} \sum_{k=0}^{N-1} X_1(k)X_2^*(k)$$

proof: $X_1(k) = \sum_{n=0}^{N-1} x_1(n)e^{-j2\pi nk/N}$

$$x_2(n) = \frac{1}{N} \sum_{k=0}^{N-1} X_2(k)e^{j2\pi nk/N}$$

$$\frac{1}{N} \sum_{k=0}^{N-1} X_1(k)X_2^*(k) = \frac{1}{N} \sum_{k=0}^{N-1} \left[\sum_{n=0}^{N-1} x_1(n)e^{-j2\pi nk/N} \right] X_2^*(k)$$

Rearrange $= \sum_{n=0}^{N-1} x_1(n) \left[\frac{1}{N} \sum_{k=0}^{N-1} X_2^*(k)e^{-j2\pi nk/N} \right]$

$$= \sum_{n=0}^{N-1} x_1(n) \left[\frac{1}{N} \sum_{k=0}^{N-1} X_2(k)e^{+j2\pi nk/N} \right]^*$$

$$\frac{1}{N} \sum_{k=0}^{N-1} X_1(k)X_2^*(k) = \sum_{n=0}^{N-1} x_1(n)x_2^*(n) // \text{ proved}$$

Problems on Circular Convolution

1] Time domain (matrix method)

If given $x(n)$ and $h(n)$

let us use matrix method of convolution.

If $h(n) = \{h(0), h(1), h(2), h(3)\}$ and $x(n) = \{x(0), x(1), x(2), x(3)\}$

$$\begin{bmatrix} h(0) & h(3) & h(2) & h(1) \\ h(1) & h(0) & h(3) & h(2) \\ h(2) & h(1) & h(0) & h(3) \\ h(3) & h(2) & h(1) & h(0) \end{bmatrix} \begin{bmatrix} x(0) \\ x(1) \\ x(2) \\ x(3) \end{bmatrix} = \begin{bmatrix} y(0) \\ y(1) \\ y(2) \\ y(3) \end{bmatrix}$$

$$y(n) = \{y(0), y(1), y(2), y(3)\}$$

2] Frequency domain $x(n)$ & $h(n)$ (matrix method)

Step 1: Find $X(K)$ and $H(K)$

" 2: $X(K)H(K)$ (element by element mul)

3: say $Y(K) = X(K)H(K)$

Step 3: Take IDFT of $Y(K)$ to obtain $y(n)$

Ex:

$$X(K)_{\text{DFT}} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -j & -1 & j \\ 1 & -1 & 1 & -j \\ 1 & j & -1 & -j \end{bmatrix} \begin{bmatrix} x(0) \\ x(1) \\ x(2) \\ x(3) \end{bmatrix} = \begin{bmatrix} X(0) \\ X(1) \\ X(2) \\ X(3) \end{bmatrix}$$

$$H(K)_{\text{DFT}} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -j & -1 & j \\ 1 & -1 & 1 & -j \\ 1 & j & -1 & -j \end{bmatrix} \begin{bmatrix} h(0) \\ h(1) \\ h(2) \\ h(3) \end{bmatrix} = \begin{bmatrix} H(0) \\ H(1) \\ H(2) \\ H(3) \end{bmatrix}$$

$$Y(K) = \begin{bmatrix} X(0) & H(0) \\ X(1) & H(1) \\ X(2) & H(2) \\ X(3) & H(3) \end{bmatrix} = \begin{bmatrix} Y(0) \\ Y(1) \\ Y(2) \\ Y(3) \end{bmatrix}$$

$$y(n) = \text{IDFT}(Y(K)) = \frac{1}{N} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & j & -1 & -j \\ 1 & -1 & 1 & -j \\ 1 & -j & -1 & j \end{bmatrix} \begin{bmatrix} Y(0) \\ Y(1) \\ Y(2) \\ Y(3) \end{bmatrix} = \begin{bmatrix} y(0) \\ y(1) \\ y(2) \\ y(3) \end{bmatrix}$$

here $N=4$

$$y(n) = \{y(0), y(1), y(2), y(3)\}$$

Both by time domain and by frequency domain $y(n)$ should be same. (Verification)

Problems on Circular Convolution

1] Time domain (matrix method)

If given $x(n)$ and $h(n)$

let us use matrix method of convolution.

If $h(n) = \{h(0), h(1), h(2), h(3)\}$ and

$x(n) = \{x(0), x(1), x(2), x(3)\}$

$$\begin{bmatrix} h(0) & h(3) & h(2) & h(1) \\ h(1) & h(0) & h(3) & h(2) \\ h(2) & h(1) & h(0) & h(3) \\ h(3) & h(2) & h(1) & h(0) \end{bmatrix} \begin{bmatrix} x(0) \\ x(1) \\ x(2) \\ x(3) \end{bmatrix} = \begin{bmatrix} x(0)h(0) + x(1)h(3) + \dots \\ \vdots \end{bmatrix}$$

$$= \begin{bmatrix} y(0) \\ y(1) \\ y(2) \\ y(3) \end{bmatrix}$$

$$y(n) = \{y(0), y(1), y(2), y(3)\}$$

2] Frequency domain $x(n)$ & $h(n)$ (matrix method)

Step 1: Find $X(K)$ and $H(K)$

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Ex:

$$X(K) = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -j & -1 & j \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{bmatrix} \begin{bmatrix} x(0) \\ x(1) \\ x(2) \\ x(3) \end{bmatrix} = \begin{bmatrix} X(0) \\ X(1) \\ X(2) \\ X(3) \end{bmatrix}$$

$$H(K) = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -j & -1 & j \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{bmatrix} \begin{bmatrix} h(0) \\ h(1) \\ h(2) \\ h(3) \end{bmatrix} = \begin{bmatrix} H(0) \\ H(1) \\ H(2) \\ H(3) \end{bmatrix}$$

$$Y(K) = \begin{bmatrix} X(0) & H(0) \\ X(1) & H(1) \\ X(2) & H(2) \\ X(3) & H(3) \end{bmatrix} = \begin{bmatrix} Y(0) \\ Y(1) \\ Y(2) \\ Y(3) \end{bmatrix}$$

$$y(n) = \text{IDFT}(Y(K)) = \frac{1}{N} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & j & -1 & j \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{bmatrix} \begin{bmatrix} Y(0) \\ Y(1) \\ Y(2) \\ Y(3) \end{bmatrix} = \begin{bmatrix} y(0) \\ y(1) \\ y(2) \\ y(3) \end{bmatrix}$$

here $N=4$

$$y(n) = \{y(0), y(1), y(2), y(3)\}$$

Both by time domain and by frequency domain $y(n)$ should be same. (Verification).

OVERLAP ADD METHOD:

↳ for finding linear convolution, segmenting given sequence

Suppose $x(n) = \{x(0), x(1), x(2), x(3), x(4), x(5), x(6), x(7), x(8), x(9)\}$

$h(n) = \{h(0), h(1), h(2)\} \rightarrow M=3 \quad M-1=2$

choose segment length $L_s=5$ (We can vary)

1st Segment $[x(0), x(1), x(2), 0, 0]$

2nd Segment $[x(3), x(4), x(5), 0, 0]$

3rd " $[x(6), x(7), x(8), 0, 0]$

4th " $[x(9), 0, 0, 0, 0]$

1st Segment						
$h(0)$	0	0	$h(2)$	$h(1)$	$x(0)$	a
$h(1)$	$h(0)$	0	0	$h(2)$	$x(1)$	b
$h(2)$	$h(1)$	$h(0)$	0	0	$x(2)$	c
0	$h(2)$	$h(1)$	$h(0)$	0	0	d
0	0	$h(2)$	$h(1)$	$h(0)$	0	e

① $y(n)$

2nd Segment						
$h(0)$	0	0	$h(2)$	$h(1)$	$x(3)$	f
$h(1)$	$h(0)$	0	0	$h(2)$	$x(4)$	g
$h(2)$	$h(1)$	$h(0)$	0	0	$x(5)$	h
0	$h(2)$	$h(1)$	$h(0)$	0	0	i
0	0	$h(2)$	$h(1)$	$h(0)$	0	j

② $y(n)$

3rd Segment				
same as previous	$x(6)$	=	k	③
	$x(7)$	=	l	
	$x(8)$	=	m	
	0	=	n	
	0	=	o	

4th Segment				
same as previous	$x(9)$	=	p	④
	0	=	q	
	0	=	r	
	0	=	s	
	0	=	t	

→ 2 overlapping as $M-1=2$

① a b c d e
② f g h i j
③ k l m n o
④ p q r s t

a b c (d+f) (e+g) h (i+k) (j+l) m (n+p) (o+q) r s t

$y(n) = \{a, b, c, (d+f), (e+g), h, (i+k), (j+l), m, (n+p), (o+q), r, s, t\}$

OVERLAP SAVE METHOD: (Segmented method)

↳ To find linear convolutⁿ.

$$x(n) = \{x(0), x(1), x(2), x(3), x(4), x(5), x(6)\}$$

$$h(n) = \{h(0), h(1), h(2)\} \Rightarrow M=3,$$

$$y(n) = ?$$

$$y(n) = ?$$

$$M-1$$

$$\begin{bmatrix} 0 & 0 & x(0) & x(1) & x(2) \end{bmatrix}$$

zeros

$$\begin{bmatrix} x(0) & x(1) & x(2) & x(3) & x(4) & x(5) \end{bmatrix}$$

$$\begin{bmatrix} x(1) & x(2) & x(3) & x(4) & x(5) \end{bmatrix}$$

$$\begin{bmatrix} x(4) & x(5) & x(6) & x(7) & x(8) \end{bmatrix}$$

$$\begin{bmatrix} x(7) & x(8) & x(9) & x(10) & 0 \end{bmatrix}$$

↳ rule for Segmentatⁿ

$$\begin{bmatrix} h(0) & 0 & 0 & h(2) & h(2) \\ h(1) & h(0) & 0 & 0 & h(2) \\ h(2) & h(1) & h(0) & 0 & 0 \\ 0 & h(2) & h(1) & h(0) & 0 \\ 0 & 0 & h(2) & h(1) & h(0) \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ x(0) \\ x(1) \\ x(2) \end{bmatrix} = \begin{bmatrix} a \\ b \\ c \\ d \\ e \end{bmatrix}$$

$$\begin{bmatrix} h(0) \\ \text{same as previous segment} \end{bmatrix} \begin{bmatrix} x(1) \\ x(2) \\ x(3) \\ x(4) \\ x(5) \end{bmatrix} = \begin{bmatrix} f \\ g \\ h \\ i \\ j \end{bmatrix}$$

$$\begin{bmatrix} \text{same as 1st} \\ \text{" one segment} \end{bmatrix} \begin{bmatrix} x(4) \\ x(5) \\ x(6) \\ x(7) \\ x(8) \end{bmatrix} = \begin{bmatrix} k \\ l \\ m \\ n \\ o \end{bmatrix}$$

$$\begin{bmatrix} \text{same as} \\ \text{1st segment} \end{bmatrix} \begin{bmatrix} x(7) \\ x(8) \\ x(9) \\ x(10) \\ 0 \end{bmatrix} = \begin{bmatrix} p \\ q \\ r \\ s \\ t \end{bmatrix}$$

as $M-1=2$, discard 1st 2 element of all matrix

i.e. (a, b, f, g, k, l, p, q)

$$y(n) = \{c, d, e, h, i, j, m, n, o, r, s, t\}$$

$$y(n) = \{y(0), y(1), y(2), y(3), y(4), y(5), y(6), y(7), y(8), y(9), y(10), y(11)\}$$

RELATIONSHIP OF DFT TO OTHER TRANSFORMS.

1] DTFT to DFT

By defn

$$\uparrow \text{DTFT is } X(e^{j\omega}) = \sum_{n=0}^{N-1} x(n)e^{-j\omega n} \quad n=0,1,\dots,N-1$$

$$\text{DFT is } X(k) = \sum_{n=0}^{N-1} x(n)e^{-j2\pi nk/N}$$

$$X(k) = X(\omega) \text{ @ } \omega = \frac{2\pi k}{N}, \quad k=0,1,2,3,\dots,N-1$$

$\therefore$ If we want to find DFT, we have to evaluate DTFT @ $k = \frac{2\pi k}{N}$

2] Z Transform to DFT:

$$\rightarrow X(z) = \sum_{n=0}^{N-1} x(n)z^{-n} \rightarrow \textcircled{1}$$

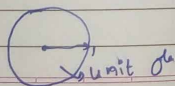
$$\text{DFT } X(k) = \sum_{n=0}^{N-1} x(n)e^{-j2\pi nk/N} \rightarrow \textcircled{2}$$

from ① & ②

$$\text{w.k.T } |e^{j2\pi k/N}| = 1 \quad |e^{j2\pi k/N}| = 1 \quad \omega = \frac{2\pi k}{N}$$

$\therefore$ On comparing 1 & 2

$$\therefore Z = e^{j2\pi k/N}$$



$$X(k) = X(z) \text{ @ } z = e^{j2\pi k/N}$$

$\therefore$ On unit circle evaluation is performed, N values are equally spaced

3] FS to DFT:

W.K.T

$$x_p(n) = \sum_{k=0}^{N-1} C_k e^{j2\pi nk/N} \rightarrow \text{periodic sig} \rightarrow \textcircled{1}$$

where C_k are Fourier coeff

$$C_k = \frac{1}{N} \sum_{n=0}^{N-1} x_p(n) e^{-j2\pi nk/N} \rightarrow \textcircled{2}$$

$$x(n) = x_p(n) \rightarrow 0 \leq n \leq N-1$$

= 0 $\rightarrow$ otherwise

becoz of this rlnship

$$C_k = \frac{1}{N} X(k) \rightarrow \textcircled{3}$$

$$X(k) = \sum_{n=0}^{N-1} x(n) e^{-j2\pi nk/N}$$

compare eq 1 & 2

$$\rightarrow X(k) = NC_k //$$

CHAPTER - 2

FAST FOURIER TRANSFORM (FFT) ALGORITHMS

Date: / /
Page No.:

→ In this we have 2 algorithms:

DIT: Decimation in time

DIF: Decimation in frequency

→ FFT is tool to find discrete fourier transform (DFT) efficiently

→ In this the symmetry property of the twiddle factors is used

* Symmetry property is:

$$1) w_N^{k+N/2} = -w_N^k$$

* Periodicity property is:

$$w_N^{k+N} = w_N^k$$

$$w_N = e^{-j\frac{2\pi}{N}}$$

→ In FFT, the number of complex multiplications are $\frac{N}{2} \log_2 N$

→ In FFT, the number of complex additions are $N \log_2 N$

$$2 \log_2 N$$

$$2^1$$

DIT (Decimation in Time): FFT algorithm

→ We use following properties to DIT

1) Symmetry:

$$w_N^{k+N/2} = -w_N^k$$

2) Periodicity

$$w_N^{k+N} = w_N^k$$

Radix 2 DITFFT Algorithm

$$N = 2^M$$

Ex: 4, 8, 16, ... 2048

In case of DITFFT

$x(n)$

even odd

$$x_e(n) = x(2n)$$

$$x_o(n) = x(2n+1)$$

Derivation of DITFFT

$$\text{w.k.T } X(K) = \sum_{n=0}^{N-1} x(n) e^{-j\frac{2\pi}{N}Kn} = \sum_{n=0}^{N-1} x(n) w_N^{nK}$$

$$= \sum_{n=0}^{N-1} x(n) w_N^{nK} + \sum_{n=0}^{N-1} x(n) w_N^{nK}$$

$$= \sum_{n=0}^{N-1} x(2n) w_N^{2nK} + \sum_{n=0}^{N-1} x(2n+1) w_N^{(2n+1)K}$$

$$= \sum_{n=0}^{N/2-1} x(2n) w_N^{2nK} + w_N^K \sum_{n=0}^{N/2-1} x(2n+1) w_N^{2nK}$$

$$X(K) = \sum_{n=0}^{N/2-1} x_e(n) w_N^{2nK} + w_N^K \sum_{n=0}^{N/2-1} x_o(n) w_N^{2nK}$$

Suppose $N=4$, $W_N^0, W_N^1, W_N^2, W_N^3$
 $1, -j, -1, j$

$$W_N^2 = \left[e^{-j\frac{2\pi}{4}} \right]^2 = W_{N/2}^2$$

$$X(k) = \sum_{n=0}^{N-1} x(n) W_N^{nk} = \sum_{n=0}^{N/2-1} x_e(n) W_{N/2}^{nk} + W_N^k \sum_{n=0}^{N/2-1} x_o(n) W_{N/2}^{nk}$$

$$X(k) = X_e(k) + W_N^k X_o(k)$$

$\xrightarrow{\frac{N}{2} \text{ pt DFT}} \quad \xrightarrow{\frac{N}{2} \text{ pt DFT}}$

Let us symbolise $X(k)$ as

$$X(k) = \underbrace{G(k)}_{x(n)_{\text{even}}} + W_N^k \underbrace{H(k)}_{x(n)_{\text{odd}}}$$

$$W_N^{k+N/2} = -W_N^k$$

$$X(k) = G(k) + W_N^k H(k)$$

$$X(k) X(k + \frac{N}{2}) = G(k + \frac{N}{2}) + W_N^{k + \frac{N}{2}} H(k + \frac{N}{2})$$

Break $G(k)$ & $H(k)$ into $\frac{N}{4}$ pt (Decimate)

$$G(k) = \sum_{r=0}^{N/2-1} g(r) W_{N/2}^{rk}$$

even $2l$ odd $2l+1$

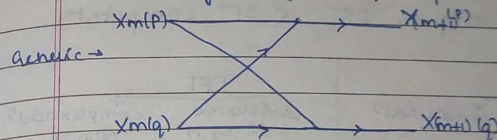
$$G(k) = \sum_{l=0}^{N/4-1} g(2l) W_{N/4}^{lk} + W_{N/2}^k \sum_{l=0}^{N/4-1} g(2l+1) W_{N/4}^{lk}$$

similarly

$$H(k) = \sum_{r=0}^{N/2-1} h(r) W_{N/2}^{rk}$$

$$H(k) = \sum_{l=0}^{N/4-1} h(2l) W_{N/4}^{lk} + W_{N/2}^k \sum_{l=0}^{N/4-1} h(2l+1) W_{N/4}^{lk}$$

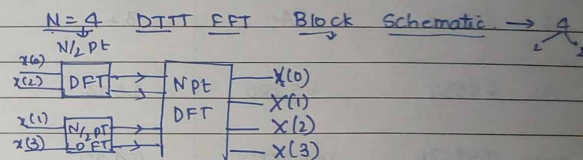
Butterfly diagram for previous eqn



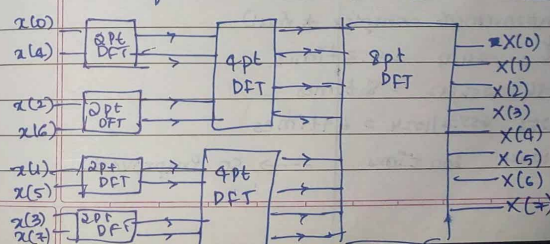
$$X_{m+1}(p) \quad X_{m+1}(q)$$

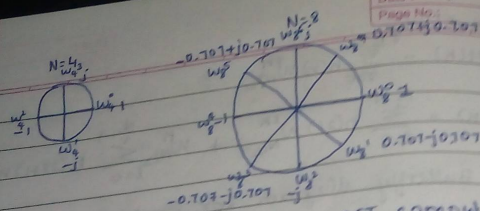
$$X_{m+1}(p) = X_m(p) + X_m(q)$$

$$X_{m+1}(q) = [X_m(p) - X_m(q)] W_N^1$$



for $N=8$ DIT FFT Block schematic $\rightarrow$





Now we compare DFT & FFT computation.

N	DET	Complex Add ⁿ	FFT	Complex Add ⁿ
	complex mul $\frac{N^2}{4}$	$N(N-1)$	complex mul $\frac{N^2}{2} \log_2 N$	$N \log_2 N$
8	64	52	12	24
16	256	240	32	64
256	65536	65280	1024	2048
1024	1048576	1047552	5120	10240

Speed Improvement complex * mul

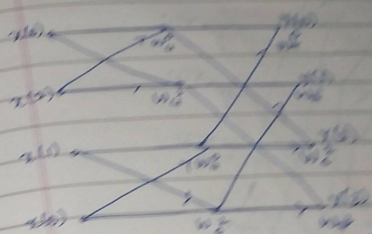
$N=8, \quad 64/12 = 5.3 \text{ times}$

$N=16, \quad 256/32 = 8 \text{ times}$

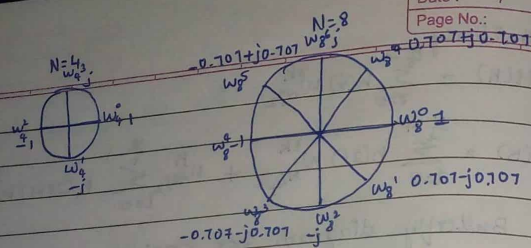
$N=256, \quad 65536/1024 = 64 \text{ times}$

$N=1024, \quad 1048576/10240 \rightarrow 102 \text{ times}$

Signed 8-bit samples



Stage 1
 $N=8 \Rightarrow 4$
Stage 2
Stage 3



Now we compare DFT & FFT computation.

N	DFT		FFT	
	complex mul ($\times$) N^2	Complex Addn + $N(N-1)$	Complex mul $\frac{N}{2} \log_2 N$	Complex addn $N \log_2 N$
8	64	52	12	24
16	256	240	32	64
256	65536	65280	1024	2048
1024	1048576	1047552	5120	10240

Speed improvement complex $\times$ (mul)

$N=8$, $64/12 = 5.3$ times

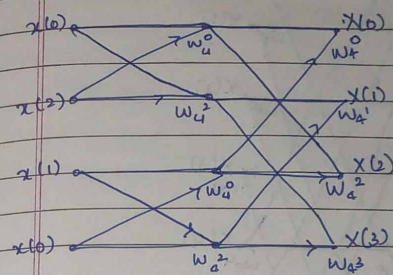
$N=16$, $256/32 = 8$ times

$N=256$, $65536/1024 = 64$ times

$N=1024$, 2048 times

→ So improved.

Signal flow graph $N=4$ pt DITFFT



Stage 1

$N=4 = 2^2$

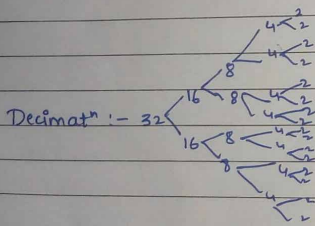
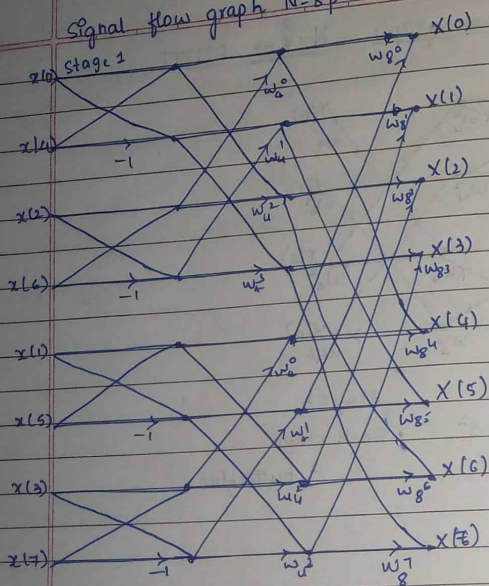
2 stage

stage 2

Each stage

2 butterfly

Signal flow graph N=8pt DITFFT



Decimation in Frequency (DIF) FFT Algorithm:

Input values are in order

Output values are bit reversed.

→ Derivatⁿ

By defn $X(k) = \sum_{n=0}^{N-1} x(n) w_N^{kn}$

$$X(k) = \sum_{n=0}^{N/2-1} x(n) w_N^{kn} + \sum_{n=N/2}^{N-1} x(n) w_N^{kn}$$

let $r = n - N/2$

$$X(k) = \sum_{n=0}^{N/2-1} x(n) w_N^{kn} + \sum_{r=0}^{N/2-1} x(r+N/2) w_N^{k(r+N/2)}$$

r is dummy variable $\therefore r$ is replaced by n

$$\therefore X(k) = \sum_{n=0}^{N/2-1} x(n) w_N^{kn} + \sum_{n=0}^{N/2-1} x(n+N/2) w_N^{k(n+N/2)}$$

$$w_N^{kN/2} = (-1)^k$$

$$X(k) = \sum_{n=0}^{N/2-1} [x(n) + (-1)^k x(n+N/2)] w_N^{kn}$$

even $k=2r$, $r=0,1,2, \dots, N/2-1$

$$X(2r) = \sum_{n=0}^{N/2-1} [x(n) + (-1)^{2r} x(n+N/2)] w_N^{2rn}$$

$$= \sum_{n=0}^{N/2-1} [x(n) + x(n + \frac{N}{2})] W_{N/2}^{rn}$$

odd $k = 2r+1, \quad r = 0, 1, \dots, \frac{N}{2}-1$

$$X(2r+1) = \sum_{n=0}^{N/2-1} [x(n) + (-1)^{2r+1} x(n + \frac{N}{2})] W_N^{rn} W_N^{2rn}$$

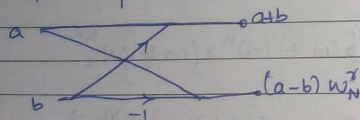
even $P(n) = x(n) + x(n + \frac{N}{2})$

odd $O(n) = [x(n) - x(n + \frac{N}{2})] W_N^n$

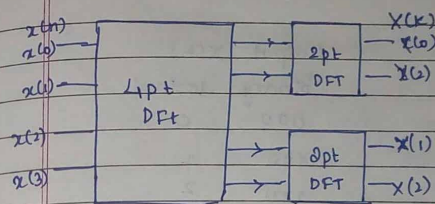
$$\therefore X(2r) = \sum_{n=0}^{N/2-1} P(n) W_{N/2}^{rn}$$

$$X(2r+1) = \sum_{n=0}^{N/2-1} O(n) W_{N/2}^{rn} \quad r = 0, 1, \dots, \frac{N}{2}-1$$

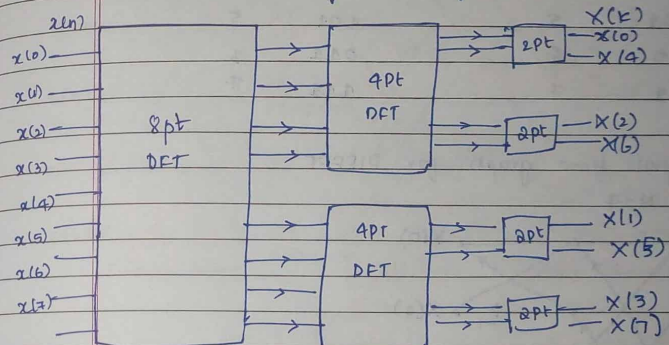
DIFFFT Butterfly pattern
Generic pattern is



Block Schematic: for $N = 4$ pt DIFFFT



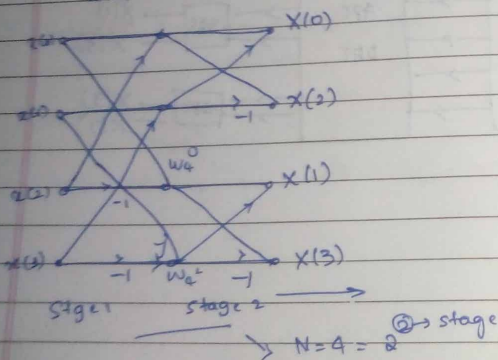
Block Schematic for $N = 8$ pt DIFFFT



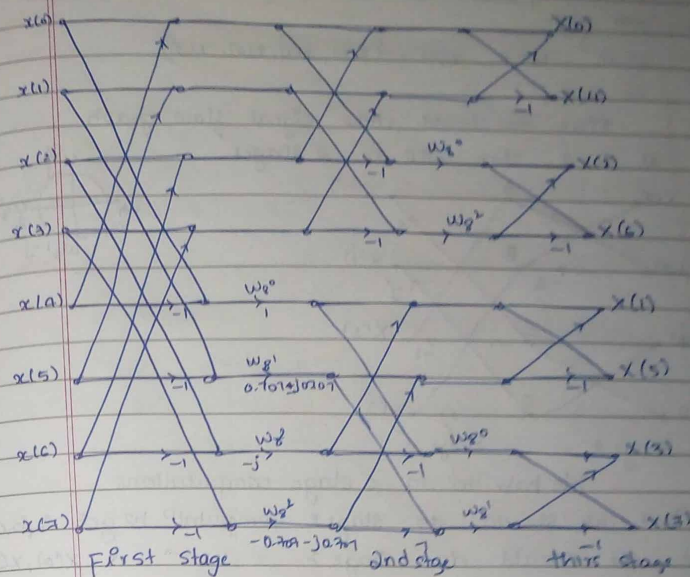
In place computation
Bit Reversed pattern

Input $x(n)$		Output $X(k)$	
Binary	decimal	Binary	decimal
000	0	000	0
001	1	100	4
010	2	010	2
011	3	110	6
100	4	001	1
101	5	101	5
110	6	011	3
111	7	111	7

Signal flow graph for DIFFFT
 $N=4$



for $N=8$



$N=8=2^3 \rightarrow$ stage

In each stage $N/2$ butterflies will be there per stage

Computational Complexity

$\frac{N \log N}{2} \rightarrow$ Complex multiplications

$\frac{N \log N}{2} \rightarrow$ Complex additions

Four Point DIT FFT and DIF FFT Algorithm

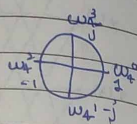
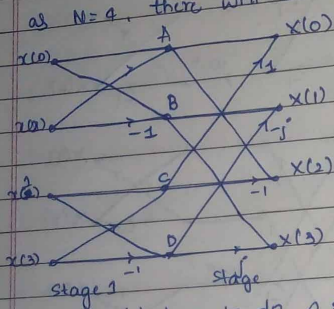
→ DIT FFT

→ Given $N=4$, $x(n) = \{x(0), x(1), x(2), x(3)\}$

To solve,

First we should draw signal flow graph

as $N=4$, there will be 2 stages



We have to do 2 stage computations

First we should do stage 1 computation to get A, B, C, D

Then we should do stage 2 " " " " $x(0), x(1)$

$x(2), x(3)$

$$A = x(0) + x(2)$$

$$X(0) = A + C$$

$$B = x(1) - x(3)$$

$$X(1) = B + D(-j)$$

$$C = x(0) - x(2)$$

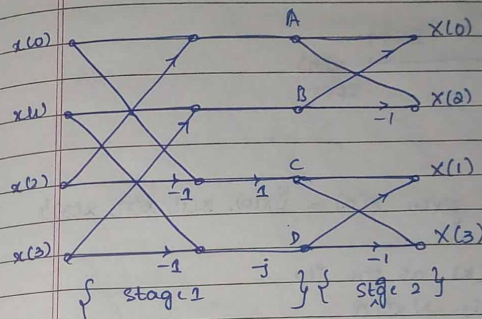
$$X(2) = A - C$$

$$D = x(1) + x(3)$$

$$X(3) = B + jD$$

$$X(k) = \{x(0), x(1), x(2), x(3)\}$$

→ DIF FFT 4 pts



$$A = x(2) + x(0)$$

$$X(0) = A + B$$

$$B = x(3) + x(1)$$

$$X(2) = A - B$$

$$C = x(0) - x(2)$$

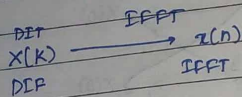
$$X(1) = C + D$$

$$D = x(1) - x(3)(-j)$$

$$X(3) = C - D$$

$$X(k) = \{x(0), x(1), x(2), x(3)\}$$

Four Point DIT IFFT and Four Point DIF IFFT Algorithm :

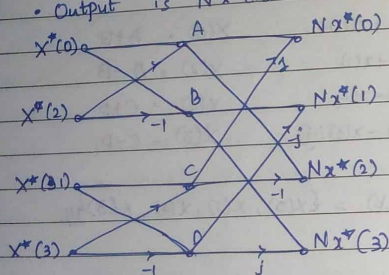


DIT IFFT :

It will be given $X(K) = \{X(0), X(1), X(2), X(3)\}$

Procedure:

- Take $X^*(K)$ as the input
- Output is $Nx^*(n)$

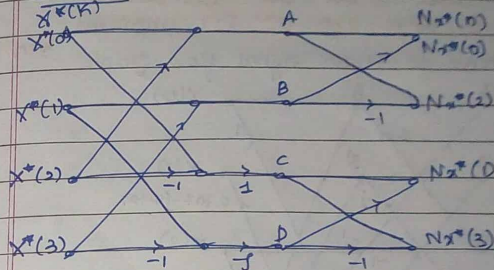


$$\begin{aligned} A &= X^*(0) + X^*(2) \\ B &= X^*(0) - X^*(2) \\ C &= X^*(1) + X^*(3) \\ D &= X^*(1) - X^*(3) \end{aligned}$$

- Take o/p $x(n) \rightarrow$ complex conjugate & divide by N to get $x(n)$

IFFT : Inverse fast fourier Transform

DIT IFFT

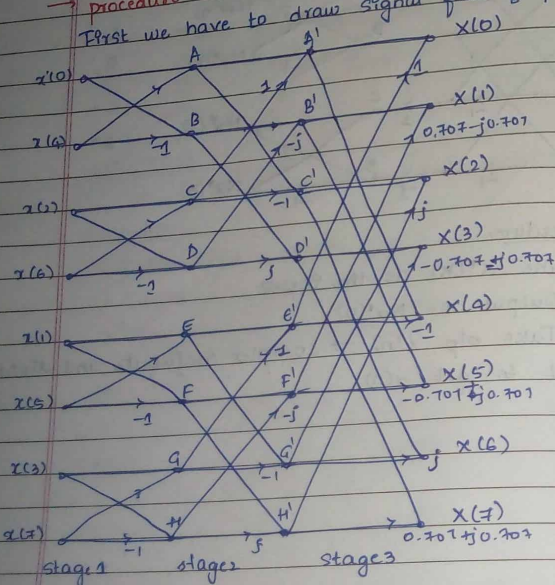


procedure:

- Take $X^*(K)$ as the input
- Output is $Nx^*(n)$
- Take o/p $x(n) \rightarrow$ complex conjugate and divide by N to get $x(n)$

8 POINT DIT FFT ALGORITHM

→ procedure to solve 8pt DIT FFT problems
First we have to draw signal flow graph $x(n)$ will be given



→ stage 1 cal's:

$$\begin{aligned} A &= x(0) + x(4) & F &= x(1) - x(5) \\ B &= x(0) - x(4) & G &= x(3) + x(7) \\ C &= x(2) + x(6) & H &= x(5) - x(7) \\ D &= x(2) - x(6) \\ E &= x(4) + x(5) \end{aligned}$$

→ stage 2 cal's:

$$\begin{aligned} A' &= A + C(j) & F' &= F + H(-j) \\ B' &= B + D(-j) & G' &= G + E(-1) \\ C' &= A + C(-1) & H' &= F + H(j) \\ D' &= B + D(j) \\ E' &= F + G \end{aligned}$$

→ stage 3 cal's

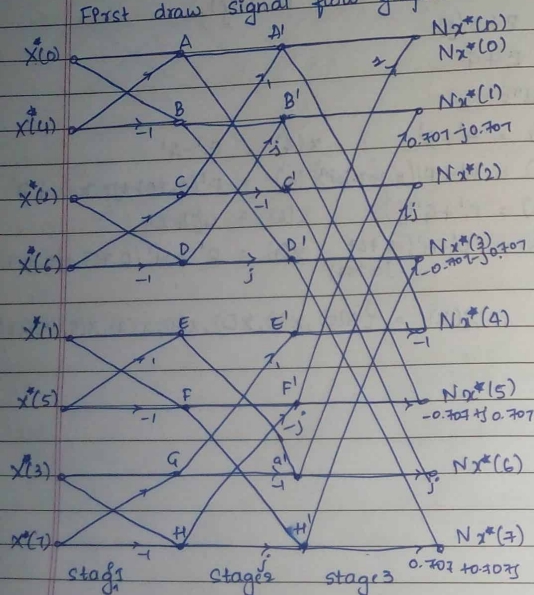
$$\begin{aligned} X(0) &= A' + E' & X(4) &= E' - A' \\ X(1) &= B' + F'(0.707-j0.707) & X(5) &= F'(0.707+j0.707) + B' \\ X(2) &= C' + G'(j) & X(6) &= G'(j) + C' \\ X(3) &= D' + H'(-0.707-j0.707) & X(7) &= D' + H'(0.707+j0.707) \end{aligned}$$

$$X(K) = \{X(0), X(1), X(2), X(3), X(4), X(5), X(6), X(7)\}$$

8 POINT DIT IFFT ALGORITHM:

→ procedure to solve 8 point DIT IFFT problems
 $X(k)$ will be given, we will find $x(n)$.

First draw signal flow graph.



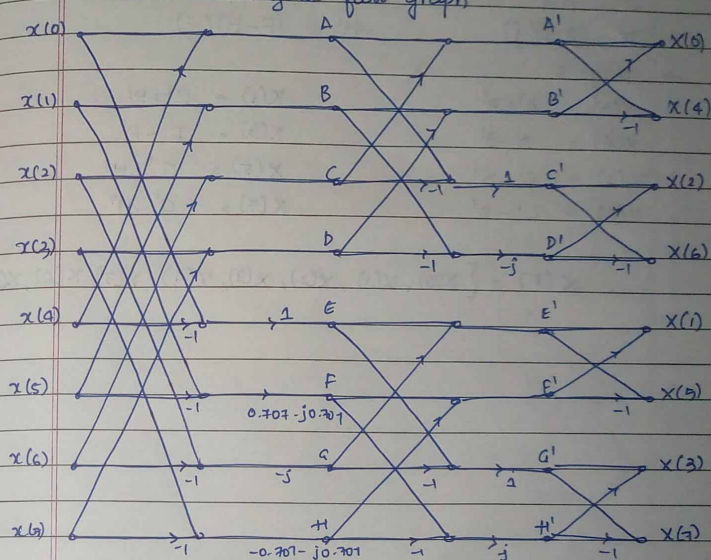
procedure

- 1) Take $X^*(k)$ as inputs
- 2) Find A, B, C, D, E, F, G, H
- 3) Find $A', B', C', D', E', F', G', H'$
- 4) Find o/p $Nx^*(n) \rightarrow$ Find $x(n)$ by taking complex conjugate & divide by $N(8)$.

8 POINT DIF FFT ALGORITHM:

→ Procedure to solve 8pt DIF FFT problems

First draw signal flow graph



→ Find A, B, C, D, E, F, G, H

→ " $A', B', C', D', E', F', G', H'$

$$\begin{aligned}
 A &= x(0) + x(4) & E &= [x(0) - x(4)]j \\
 B &= x(1) + x(5) & F &= [x(1) - x(5)](0.707 - j0.707) \\
 C &= x(2) + x(6) & G &= [x(2) - x(6)]j \\
 D &= x(3) + x(7) & H &= [x(3) - x(7)](-0.707 - j0.707)
 \end{aligned}$$

Stage 2

$$A' = A + C$$

$$B' = B + D$$

$$C' = A - C$$

$$D' = (B - D)(-j)$$

$$E' = E + G$$

$$F' = F + H$$

$$G' = E - G$$

$$H' = (F - H)(-j)$$

→ Stage 3

$$X(0) = A' + B'$$

$$X(4) = A' - B'$$

$$X(2) = C' + D'$$

$$X(6) = C' - D'$$

$$X(1) = E' + F'$$

$$X(3) = E' - F'$$

$$X(5) = G' + H'$$

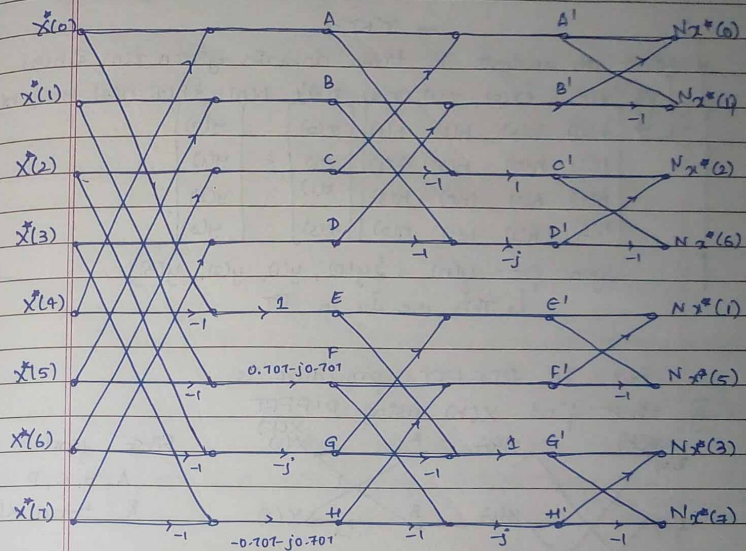
$$X(7) = G' - H'$$

$$X(K) = \{X(0), X(1), X(2), X(3), X(4), X(5), X(6), X(7)\}$$

8 POINT DIF TFFT ALGORITHM.

→ Procedure to solve 8 point DIF TFFT problems:

$$X(K) \rightarrow x(n)$$



→ Take $X^*(K)$ as flip

→ Find A, B, C, D, E, F, G, H & $A', B', C', D', E', F', G', H'$

→ Find $0/p \ N X^*(n) \rightarrow$ Find $0/p \ x(n)$ by find complex conjugating and dividing by $N (=8)$

$$x(n) = \frac{1}{N} \{X^*(0), X^*(1), X^*(2), X^*(3), X^*(4), X^*(5), X^*(6), X^*(7)\}$$

CIRCULAR CONVOLUTION USING FFT & IFFT

→ Circular convolution using DIF FFT

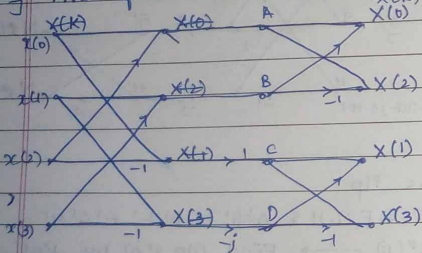
First do analysis in time domain given $x(n)$ & $h(n)$
If $x(n) = \{x(0), x(1), x(2), x(3)\}$ $h(n) = \{h(0), h(1), h(2), h(3)\}$

$$\begin{bmatrix} h(0) & h(3) & h(2) & h(1) \\ h(1) & h(0) & h(3) & h(2) \\ h(2) & h(1) & h(0) & h(3) \\ h(3) & h(2) & h(1) & h(0) \end{bmatrix} \begin{bmatrix} x(0) \\ x(1) \\ x(2) \\ x(3) \end{bmatrix} = \begin{bmatrix} y(0) \\ y(1) \\ y(2) \\ y(3) \end{bmatrix}$$

you get $y(n) = \{y(0), y(1), y(2), y(3)\}$
→ This we do in FT

But in DIF FFT procedure is

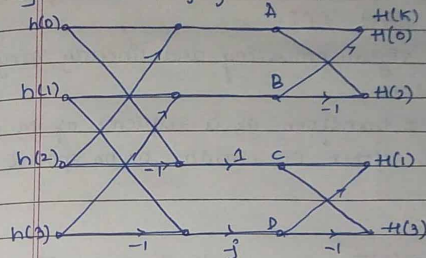
1] First find $X(k)$ using DIF FFT



$$X(k) = \{x(0), x(1), x(2), x(3)\}$$

First find
A, B, C, D
& then $X(k)$

2] Same way find $H(k)$



Find A, B, C, D and
then $H(k)$

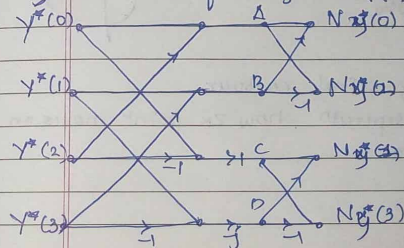
$$H(k) = \{H(0), H(1), H(2), H(3)\}$$

3] Find $Y(k) = X(k)H(k)$

$$Y(k) = \begin{bmatrix} x(0) & H(0) \\ x(1) & H(1) \\ x(2) & H(2) \\ x(3) & H(3) \end{bmatrix}$$

→ not matrix mul,
do element by
element multi-
plication

4] Now to find $y(n)$ apply DIF IFFT to $Y(k)$



here we get $N y^*(n)$
To get $y(n)$ take
complex conjugate
and divide by $N(4)$

CHIRP-Z TRANSFORM (CZT) ^{Algorithm transform}

↳ to find FFT

→ Used in radar signal processing and linearly varying frequency applications.
→ For evaluating z transform of a sequence of M pts in z plane w lie either on circular or on spiral contour in z plane.

$$X(Z_k) = \sum_{n=0}^{N-1} x(n) Z_k^{-n} \quad K=0, 1, 2, \dots, M-1$$

If this reduces to DFT

$$Z_k = e^{j2\pi k/N} = W_N^k, \quad K=0, 1, \dots, N-1$$

Let Z_k be a point of on the spiral contour centered about the origin

$$\rightarrow Z_k = AB^{-k}$$

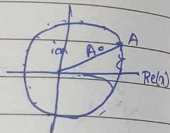
A → pt @ w spiral starts

$$A = A_0 e^{j\theta_0}$$

$$B = B_0 e^{j\phi_0}$$

B → rate of spiral contour

⇒ angular separation, how Z_k point moves on spiral



Case 1: $B_0 < 1$

$\{Z_k\} \rightarrow$ It spirals towards the origin

Case 2: $B_0 > 1$

$\{Z_k\} \rightarrow$ spirals away from the origin

Case 3: $|B_0| = 1$

$\{Z_k\} \rightarrow$ will be on circle A_0

* Special case

$$\text{If } A_0 = 1 \text{ and } B = e^{-j2\pi/N}$$

↳ $M=N$

→ It corresponds to DFT & contour is a unit circle

$$\rightarrow X(Z_k) = \sum_{n=0}^{N-1} x(n) A^{-n} B^{kn}, \quad 0 \leq k \leq N-1$$

$$\text{W.K.T } nk = \frac{1}{2} [n^2 + k^2 - (k-n)^2]$$

$$\therefore X(Z_k) = \sum_{n=0}^{N-1} x(n) A^{-n} B^{\frac{n^2}{2}} B^{\frac{k^2}{2}} B^{-\frac{(k-n)^2}{2}}$$

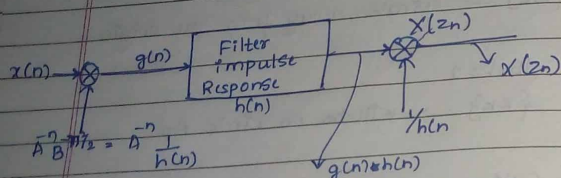
Let us consider 2 functions $g(n) = x(n) A^{-n} B^{\frac{n^2}{2}}$ and $h(n) = B^{\frac{k^2}{2}} B^{-\frac{n^2}{2}}$

$$\therefore X(Z_k) = \sum_{n=0}^{N-1} g(n) \frac{1}{h(n)} (h(k-n)) \quad 0 \leq n \leq N-1$$

Now consider

$$X(z) = \frac{1}{h(n)} [g(n) * h(n)]$$

→ This is computer of chirp Z transform algorithm



↓
Generating chirp Z Transform

$$h(n) = \left[e^{-j\phi_0} \right]^{\frac{n^2}{2}} = e^{j\frac{n^2\phi_0}{2}} = e^{j\omega n \frac{\phi_0}{2}} \quad \omega = \frac{2\phi_0}{2}$$

→ complex exponential sequence linearly increasing frequency is called "chirp".

GOERTZEL ALGORITHM :- To find DFT

- This algorithm is linear filtering technique
- Efficient tool to compute DFT when small number of frequency points are there.
- This algorithm makes use of periodicity property of W_N^{-kN}

→ Let us take, given signal $x(n)$

$$X(k) = \sum_{m=0}^{N-1} x(m) W_N^{km} W_N^{-kN}$$

$$X(k) = \sum_{m=0}^{N-1} x(m) W_N^{k(m-N)}$$

$$X(k) = \sum_{m=-\infty}^{\infty} x(m) W_N^{-k(N-m)}$$

$$\text{let } y_k(n) = \sum_{m=-\infty}^{\infty} x(m) W_N^{-(n-m)k}$$

$$X(k) = y_k(n) \big|_{n=N}$$

$$y_k(n) = x(n) * W_N^{-kn}$$

Transfer func of Goertzel filter is

$$H_k(z) = \sum_{n=0}^{\infty} h_k(n) z^{-n} = \sum_{n=0}^{\infty} (W_N^{-k} z^{-1})^n$$

WKT $\sum_{n=0}^{\infty} a^n = \frac{1}{1-a}$, $|a| < 1$

$$H_k(z) = \frac{1}{1 - W_N^k z^{-1}}$$

$$\frac{Y_k(z)}{X(z)} = \frac{1}{1 - W_N^k z^{-1}}$$

cross multiply and take inverse z transform

$$Y_k(n) = W_N^k y_k(n-1) = x(n)$$

Take $H_k(z)$ & multiply and divide by $1 - W_N^{-k} z^{-1}$

$$H_k(z) = \frac{1 - W_N^{-k} z^{-1}}{(1 - W_N^k z^{-1})(1 - W_N^{-k} z^{-1})}$$

$$H_k(z) = \frac{1 - W_N^k z^{-1}}{1 - W_N^k z^{-1} - W_N^{-k} z^{-1} + z^{-2}}$$

$$H_k(z) = \frac{1 - W_N^k z^{-1}}{1 - e^{j\frac{2\pi k}{N}} z^{-1} - e^{-j\frac{2\pi k}{N}} z^{-1} + z^{-2}}$$

$$H_k(z) = \frac{1 - W_N^k z^{-1}}{1 - 2\cos\left(\frac{2\pi k}{N}\right) z^{-1} + z^{-2}}$$

$$= H_1(z) H_2(z)$$

$$\text{Let } V_k(z) = X(z) H_1(z)$$

$$= \frac{1}{1 - 2\cos\left(\frac{2\pi k}{N}\right) z^{-1} + z^{-2}} X(z)$$

cross mul & then take inverse z transform

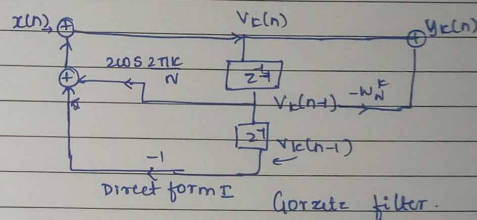
$$V_k(n) = 2\cos\left(\frac{2\pi k}{N}\right) V_k(n-1) - V_k(n-2) + x(n)$$

$$Y_k(z) = H_2(z) V_k(z)$$

$$Y_k(z) = (1 - W_N^k z^{-1}) V_k(z)$$

$$Y_k(n) = V_k(n) - W_N^k V_k(n-1)$$

$$V_k(-1), V_k(-2) \Rightarrow \text{zero}$$



→ Its an ^{very} efficient algorithm as

Each iteratⁿ will have only one real multiplicatⁿ & two addⁿs.

$x(n) \Rightarrow \text{real}$

$N+1$ real multiplicatⁿs only